



School of Computer Science & Engineering
Trustworthy Systems Group

Carrels: Secure, High-performance Microservices on seL4

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(presented by Gernot)

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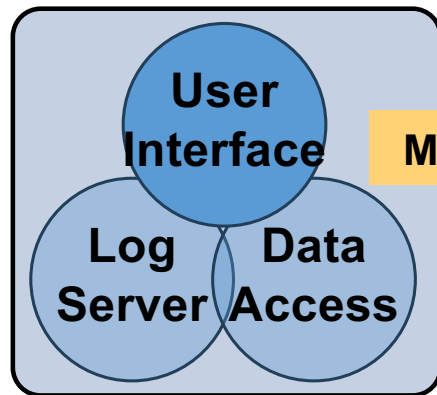


- 1. Microservices and seL4**
2. Microservice Deployment and Life-cycle
3. Orchestration
4. Programming API

Microservices



Monolithic Architecture

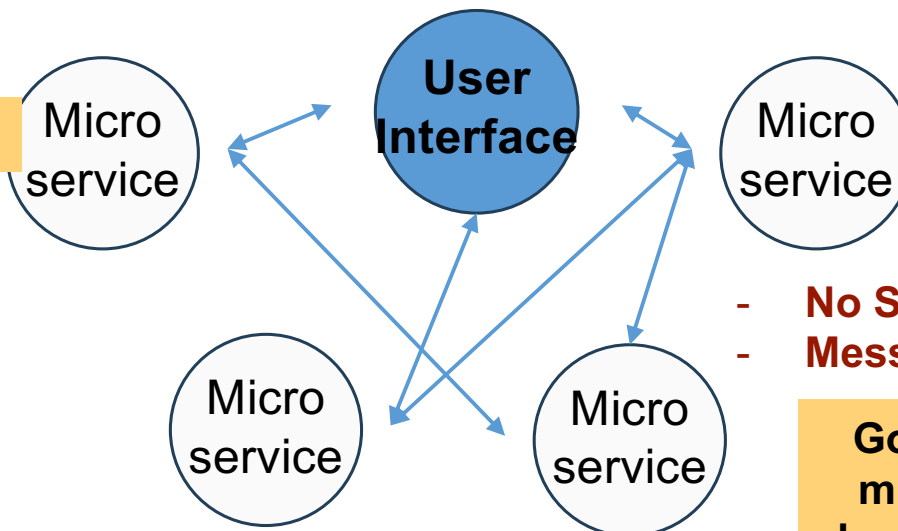


- **Strong inter-dependencies due to shared state**
- **Difficult to scale or upgrade**

More modularity



Microservice Architecture



- **No State Sharing**
- **Message-passing**

Good fit for a microkernel-based design?

seL4

Carrels: Microservices on seL4



LionsOS as starting point



Design Aspects:

1. Support microservice live-cycle changes

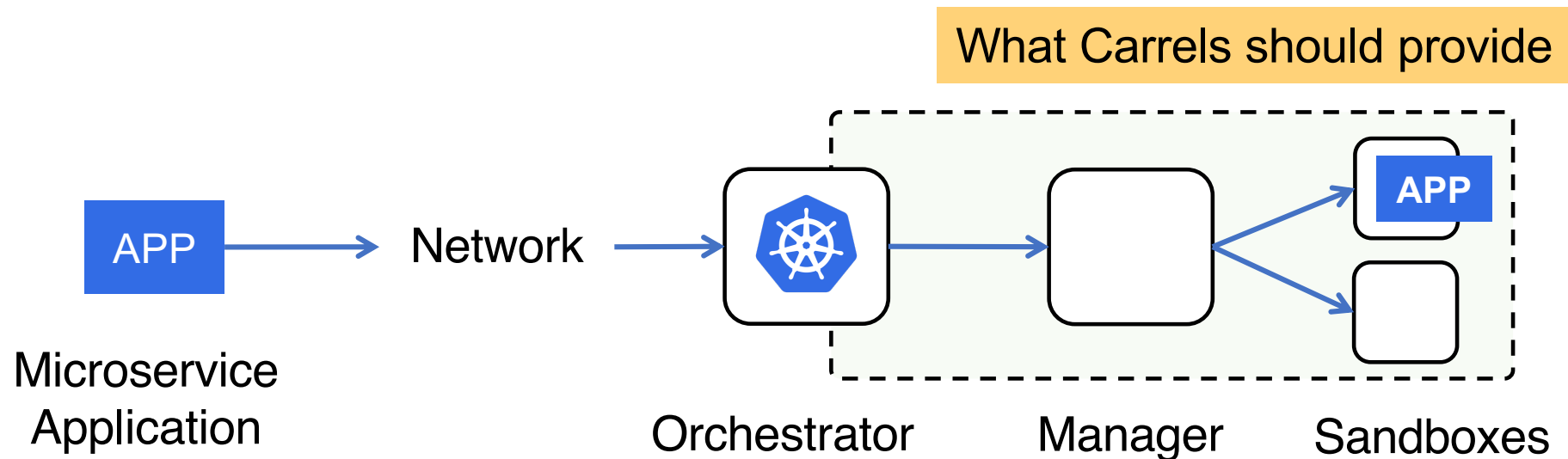
2. Orchestration: managing services

3. Familiar API



1. Microservices and seL4
- 2. Microservice deployment and life-cycle**
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Microservice Deployment Chain

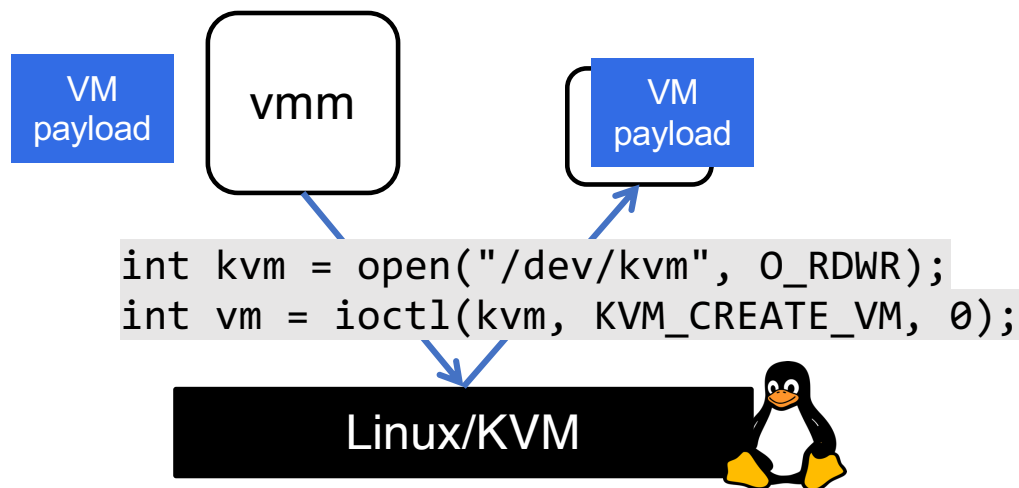


Payload Deployment in Sandboxes

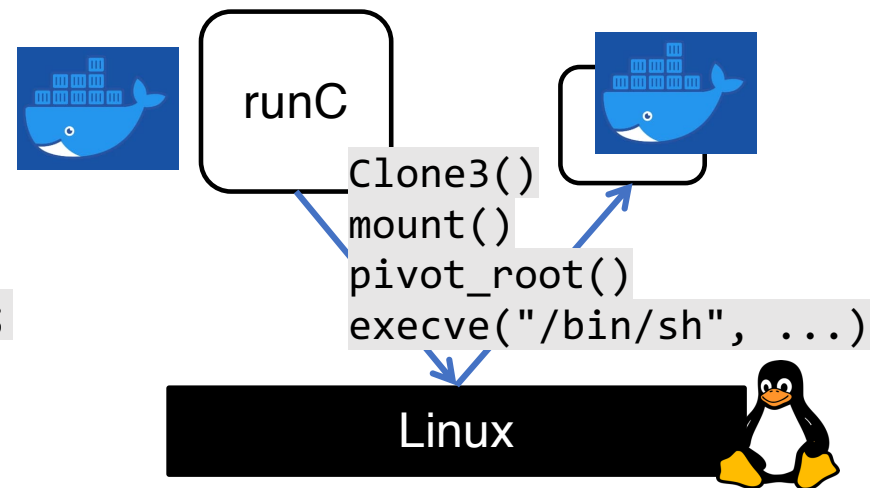


How make pattern work on seL4?

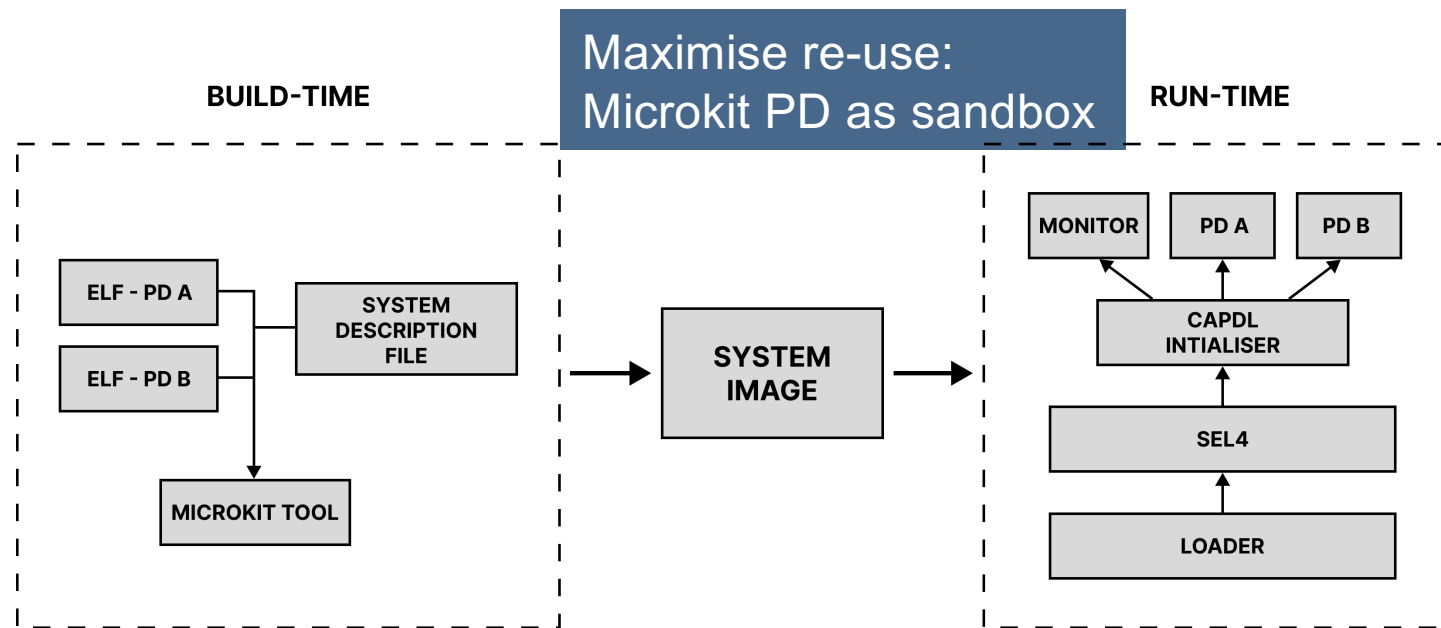
Case study: Linux VM



Case study: Linux Container



Microkit



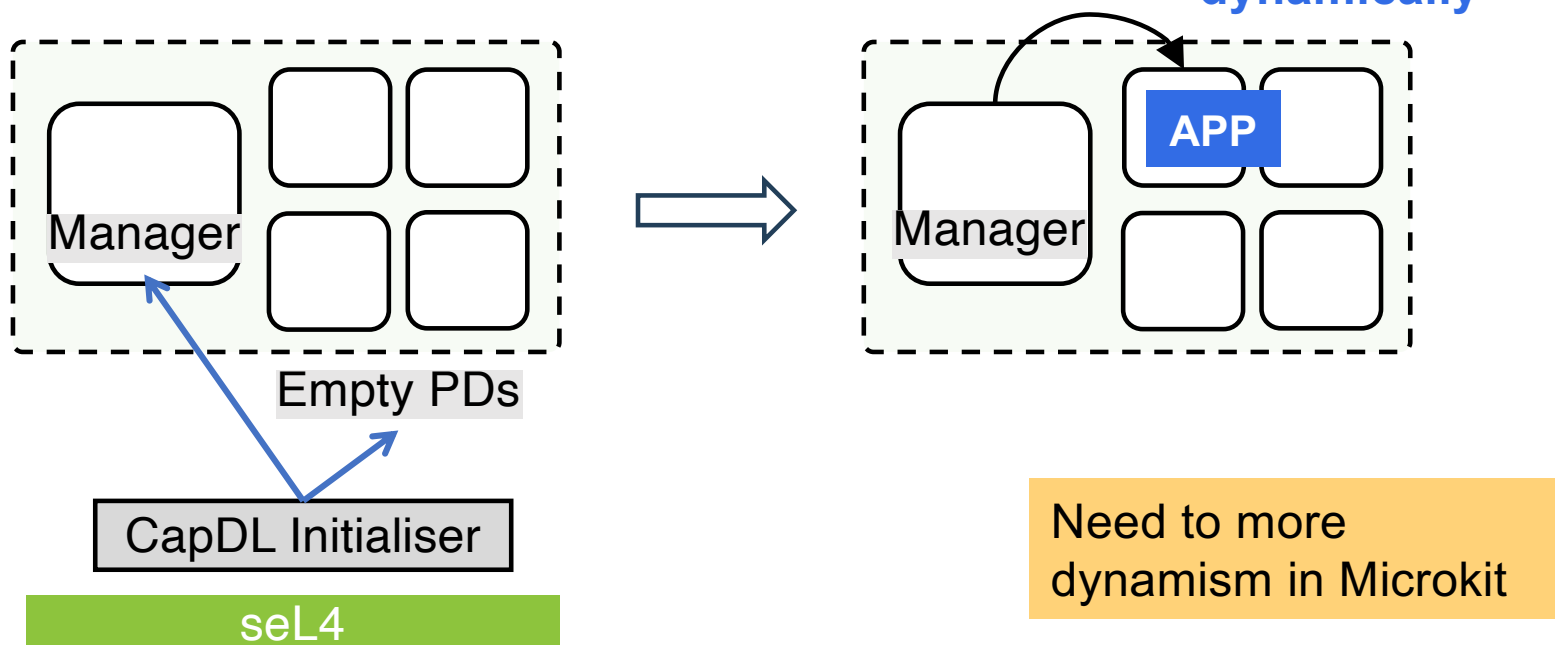
Need support for
life-cycle changes

Trusted component to
control PD changes

- ✓ Change the execution state of a PD
- Change the program image of a PD
- Change the resource view of a PD

PDs as Sandboxes

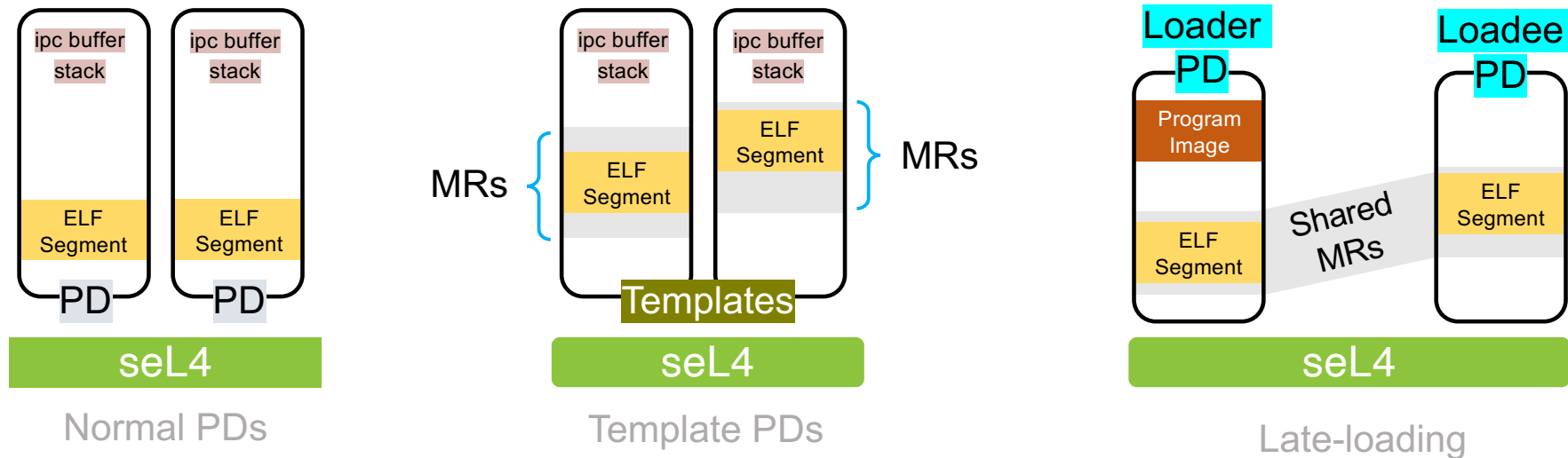
- Partition resources at boot time
- Pre-provision PDs



Loading a New Image

- **Template PD**

- PDs without an image by default



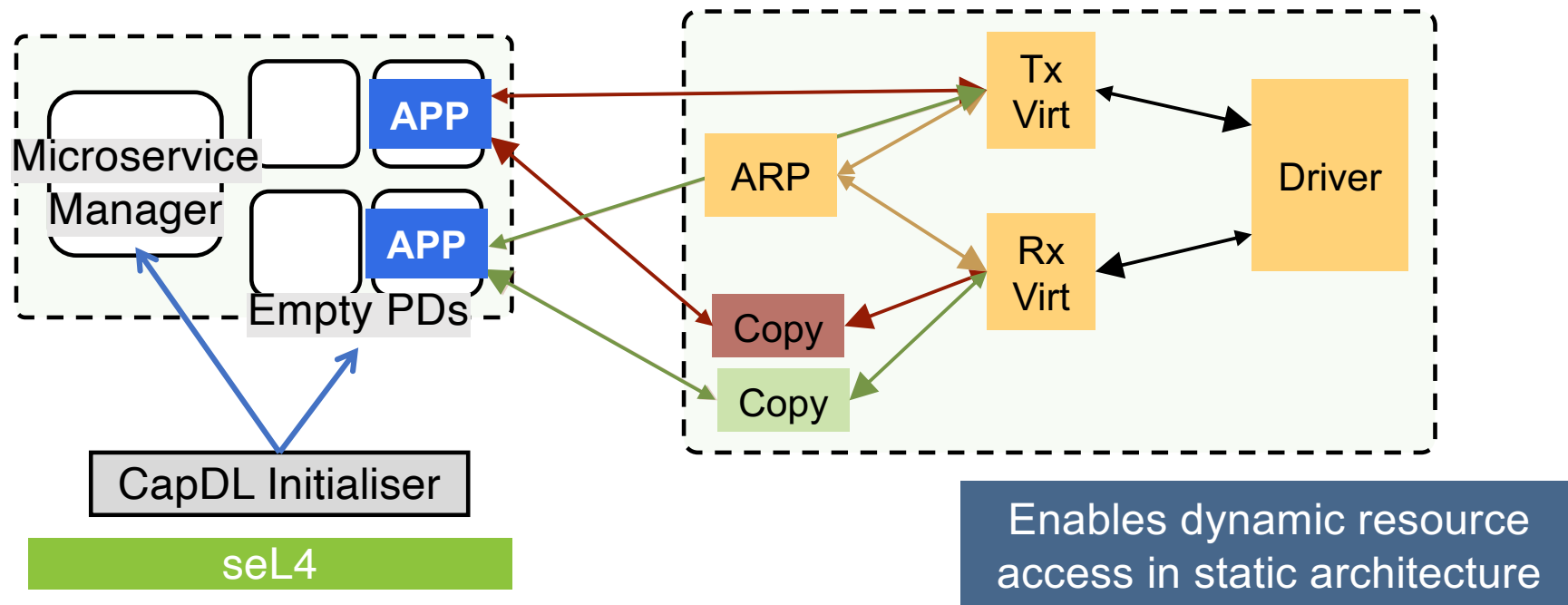
- Template PD needs a fault handler and a loader

- The loader requires access to the cap of template PD's thread control block

Resource Management

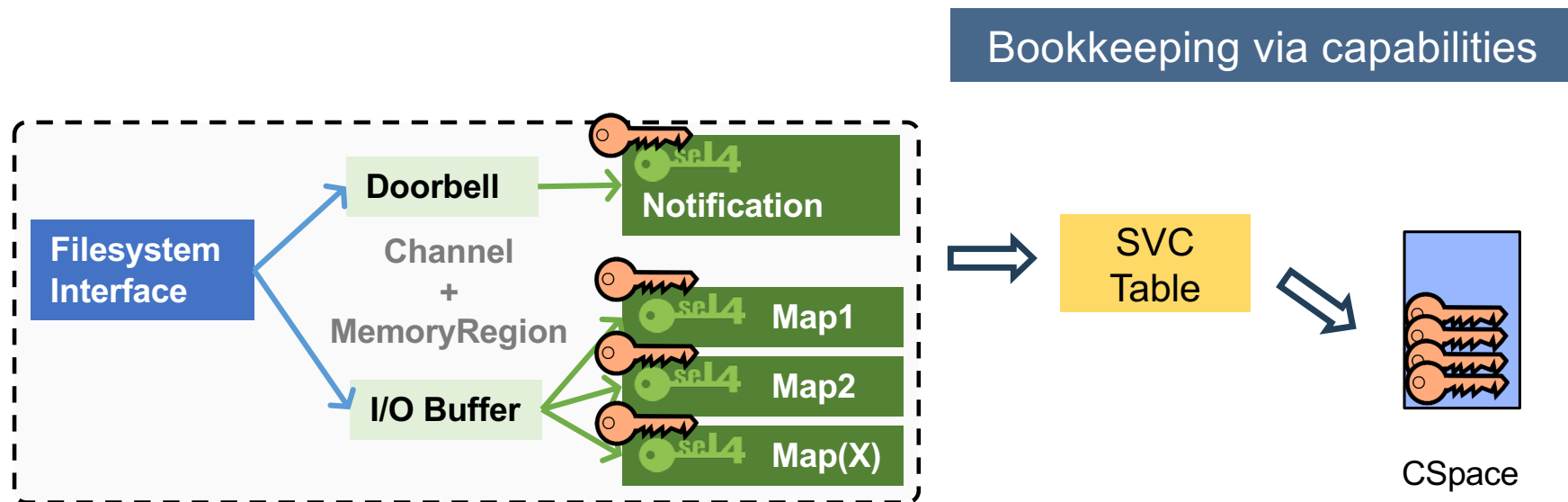


- Provision (ceiling of) connections at boot-time
- Establish authorised connections dynamically



Resource Bookkeeping

Abstract resources with Microkit abstractions Channel + MemoryRegion

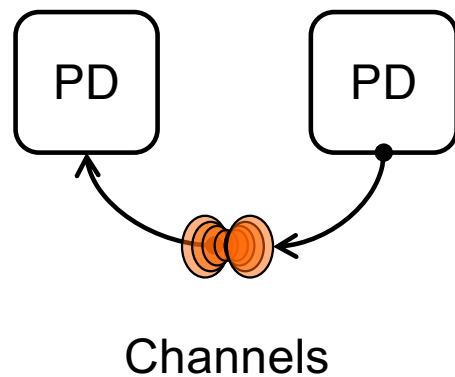


Use sdfgen/Acacia to generate SVC (services) table

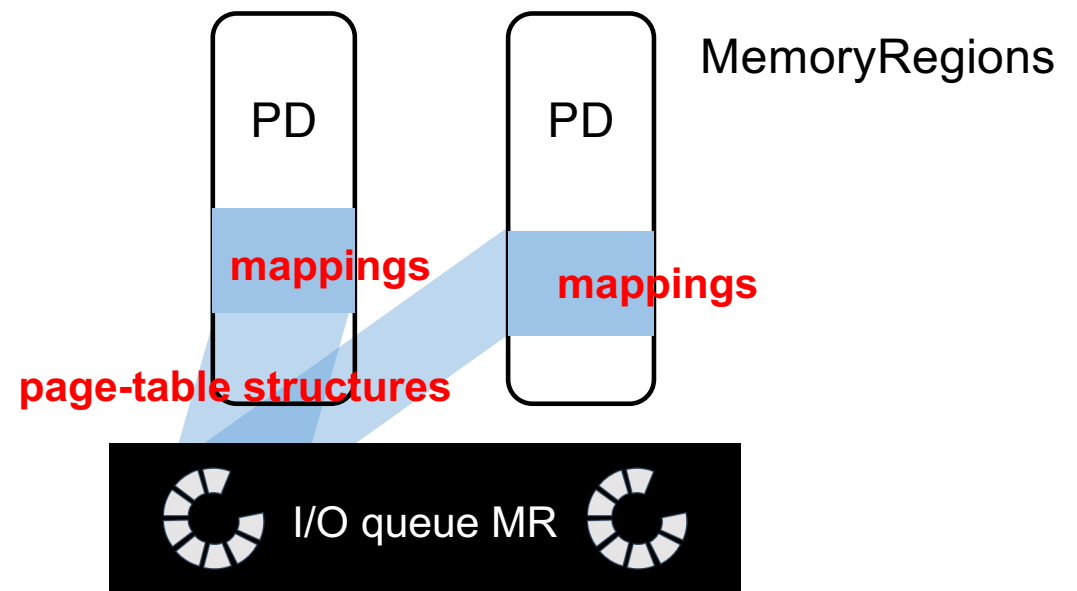
Resource Provisioning and Control



- **Pre-provision** – channel capability
- **Control** – CNode_Copy/Delete



- **Pre-provision** – frame capabilities with page-table structures
- **Control** – Page_Map/Unmap





Change the resource view of a PD

- **Capability Delegation**

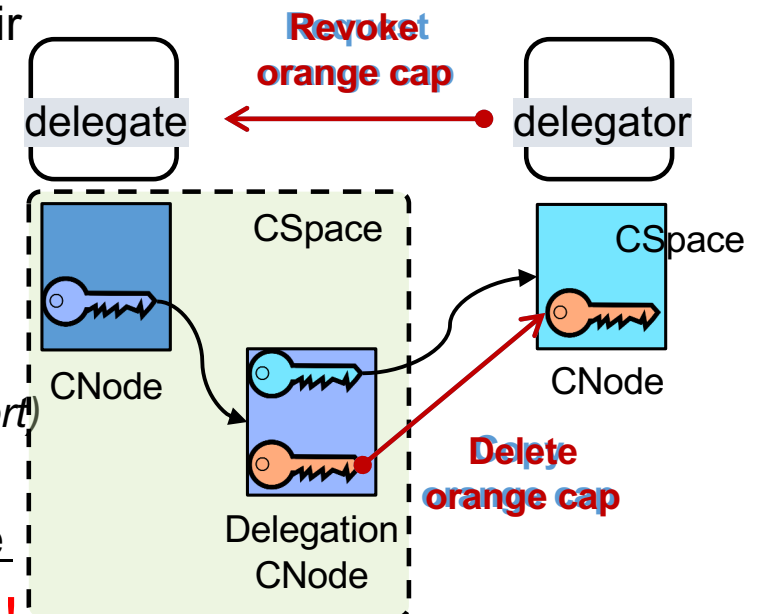
- PDs can declare rights of use of capabilities as delegated
- The delegated caps will be given to a trusted resource controller PD
- This forms a delegation(delegate, delegator) pair

Allows resources changes of PDs

- **Implementation**

- Microkit tool create a CNode for delegation
- Delegation CNode contains caps of delegator
 - VSpace
 - CSpace
 - All delegated resources (MRs, channels, x86 IOport)
- Delegation CNode is accessible to the delegate
- Each delegation pair has one delegation CNode

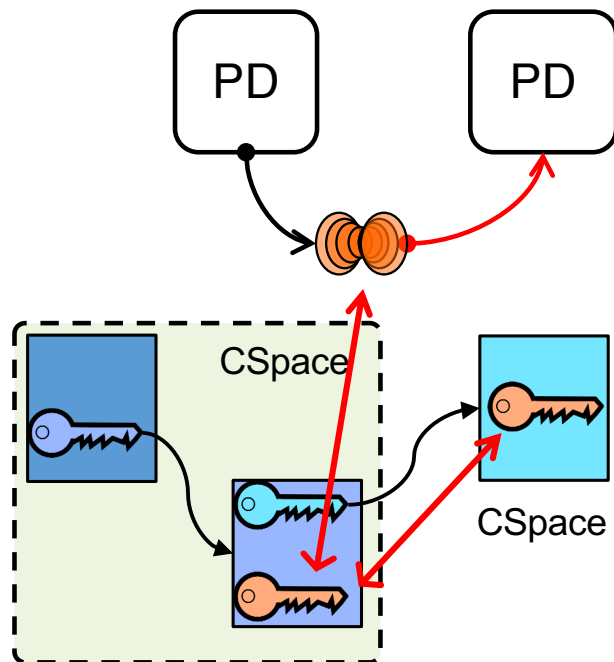
- **No runtime resource creation/reclaim allowed!!**



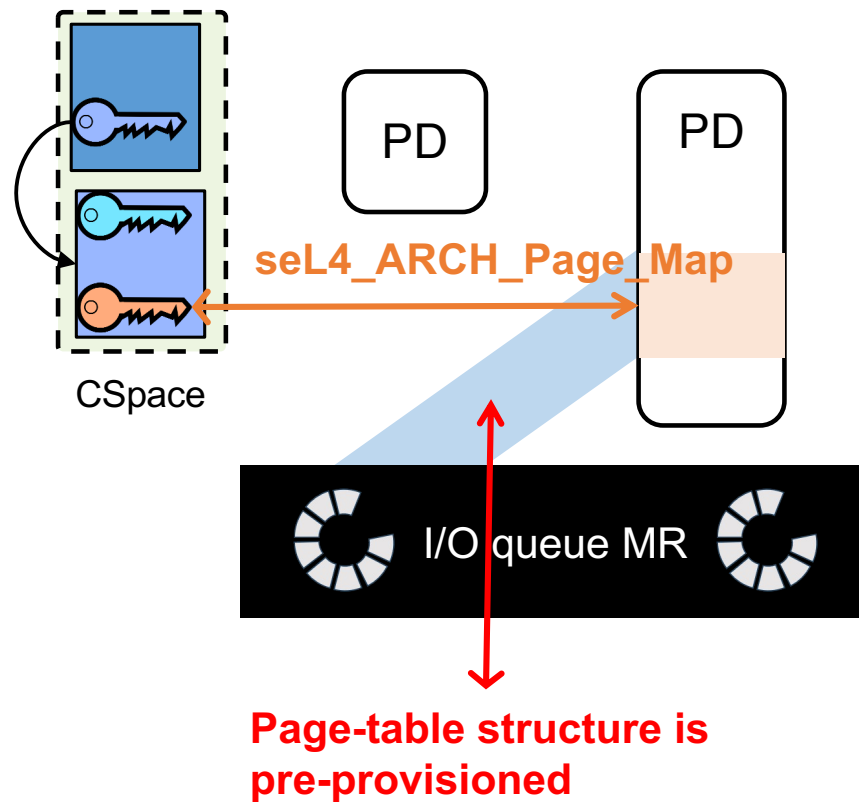
Resource Control via Cap Delegation



Channels

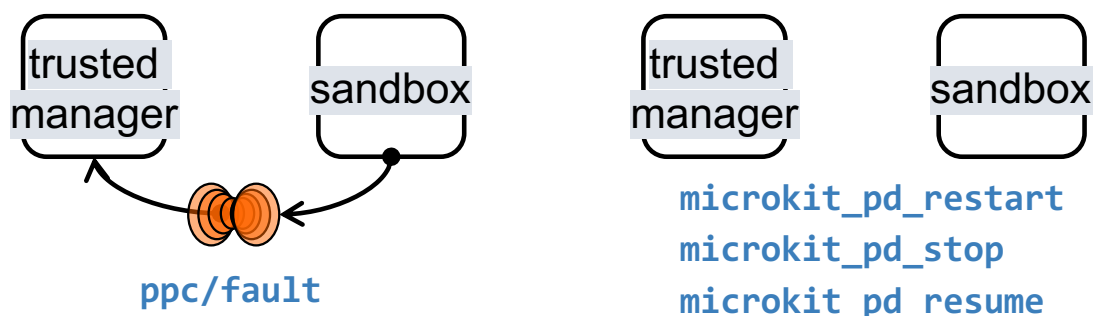


MemoryRegions

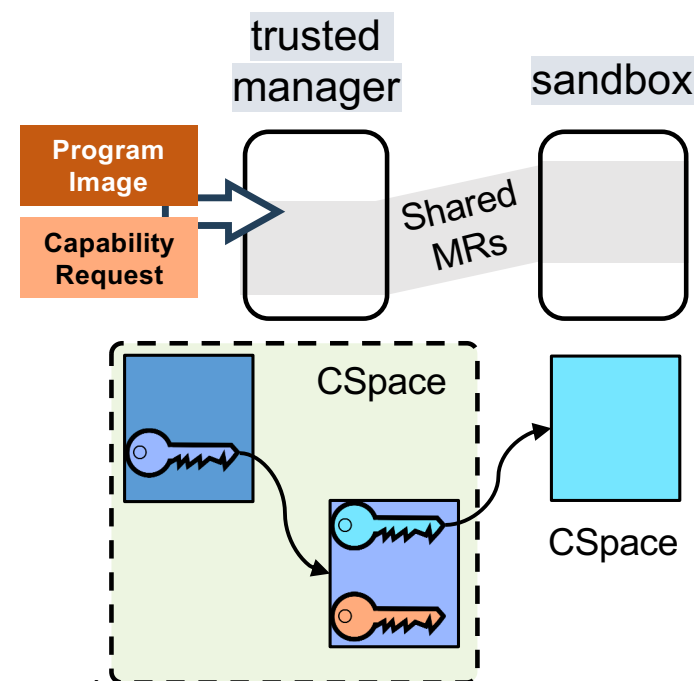


Sandbox With Dynamic Features

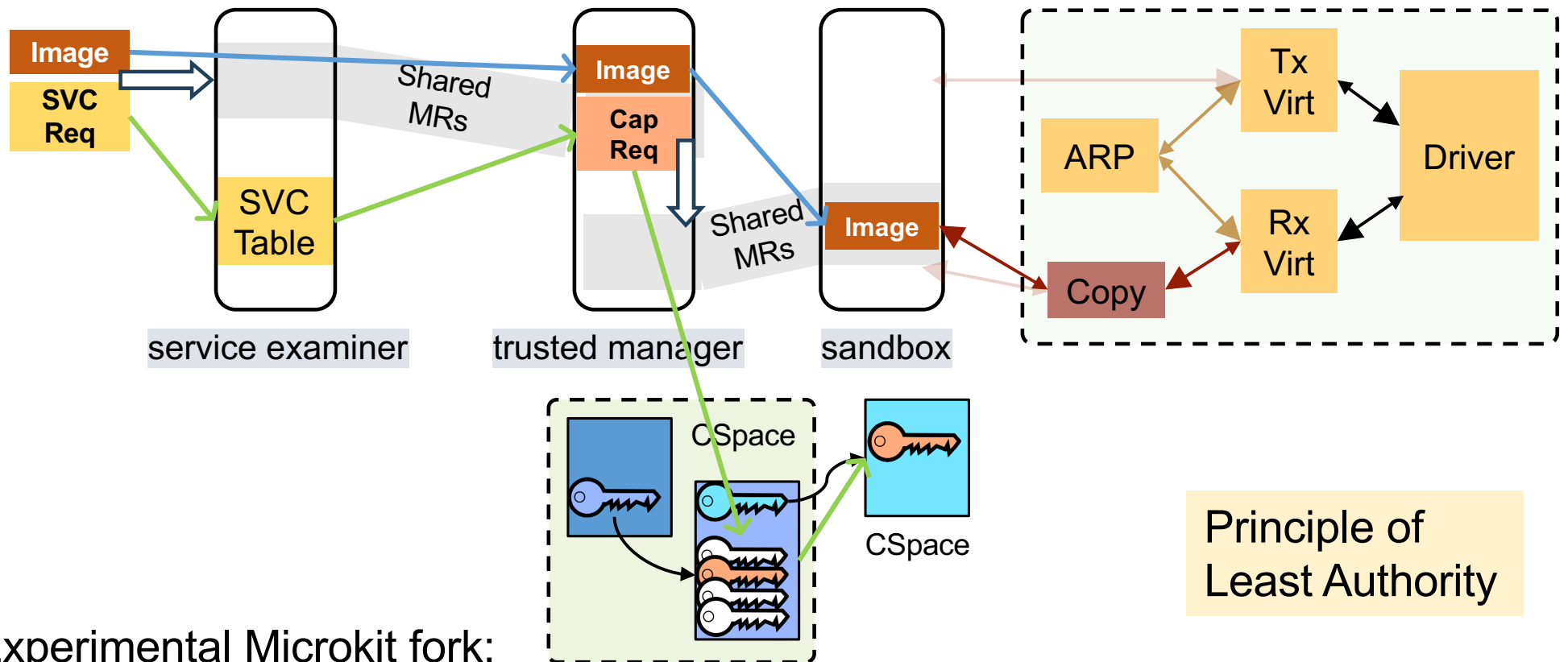
Trusted manager is delegate of template PD



- The trusted manager
 - Serves sandboxes as a server/fault handler
 - Controls the life-cycle changes of sandboxes
 - Dynamically loads program image (via shared memory)
 - Performs delegated-capability bookkeeping



Example: Using Network Rx Virtualiser



Experimental Microkit fork:

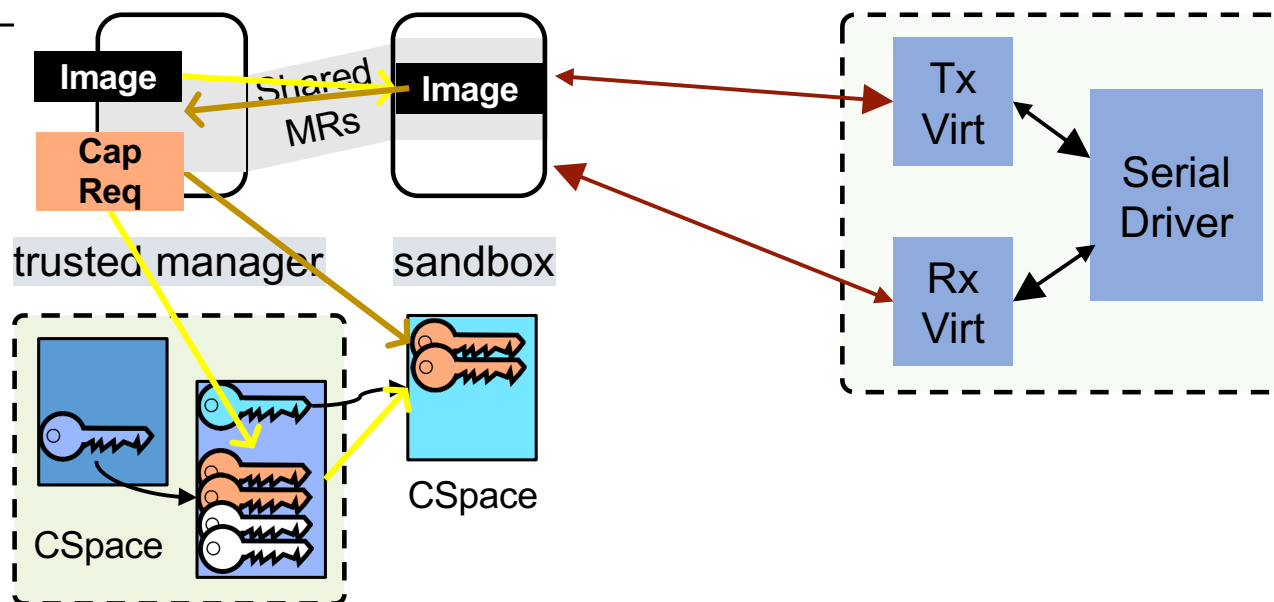
<https://github.com/au-ts/dynamic-microkit>

Preliminary Results: Startup Latency

ISA	Platform	Startup-teardown Latency
ARM64	Cortex-a55 at 1.2Ghz	284,400 cycles (237 μ s)
x86_64	Xeon® W-1250 at 3.3Ghz	139,500 cycles (42 μ s)

Payload setup

- Resource view
- (serial connection)
 - 34 frames to map
 - 1 channel to grant
- Image size
 - 156 KB in total
 - 16 KB to load



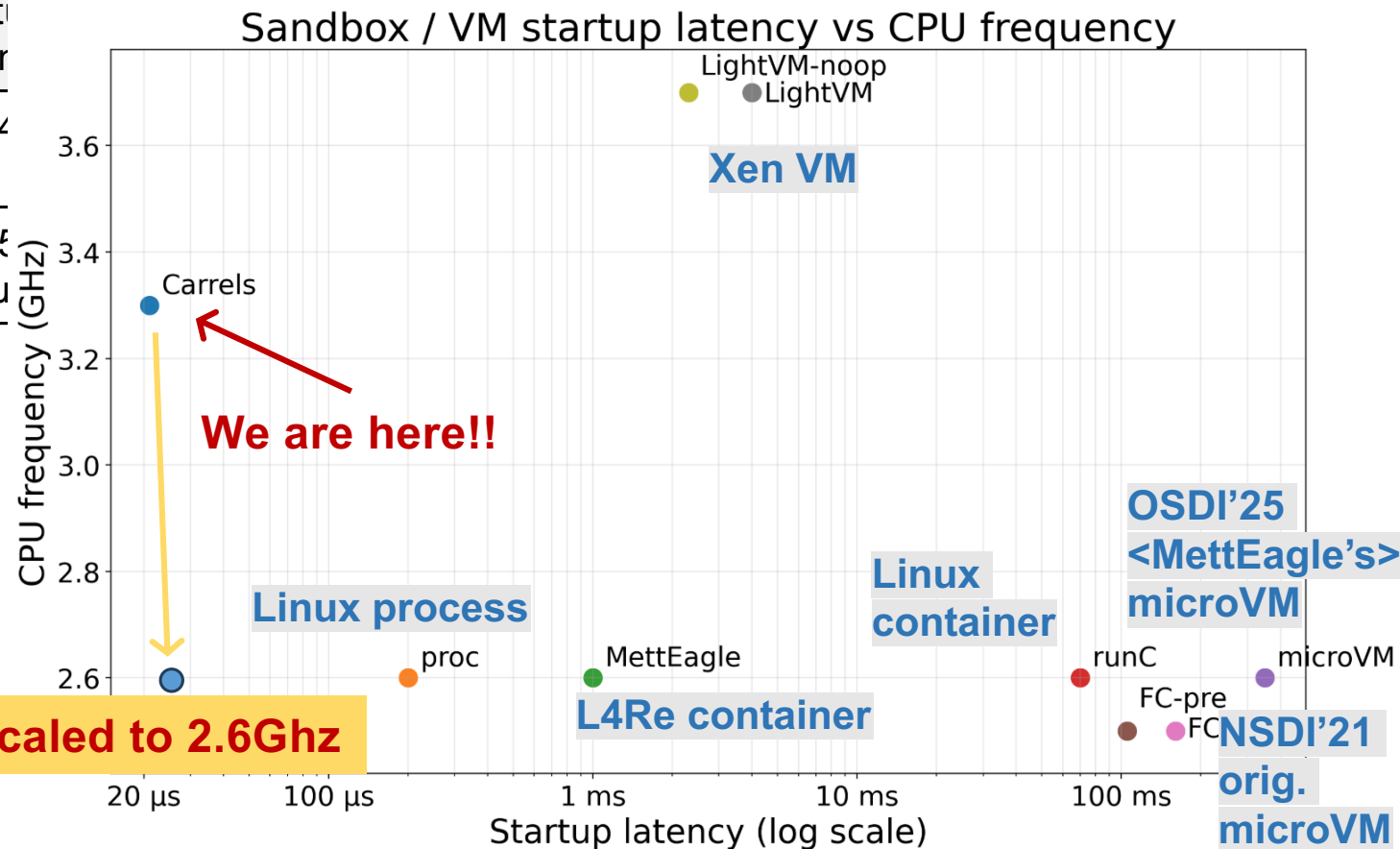
Preliminary Results: Tear-Down Latency



ISA	Platform	Start Latency
ARM64	Cortex-a55 at 1.2Ghz	284,4 (237)
x86_64	Xeon® W-1250 at 3.3Ghz	139,5 (42 μs)

Payload setup

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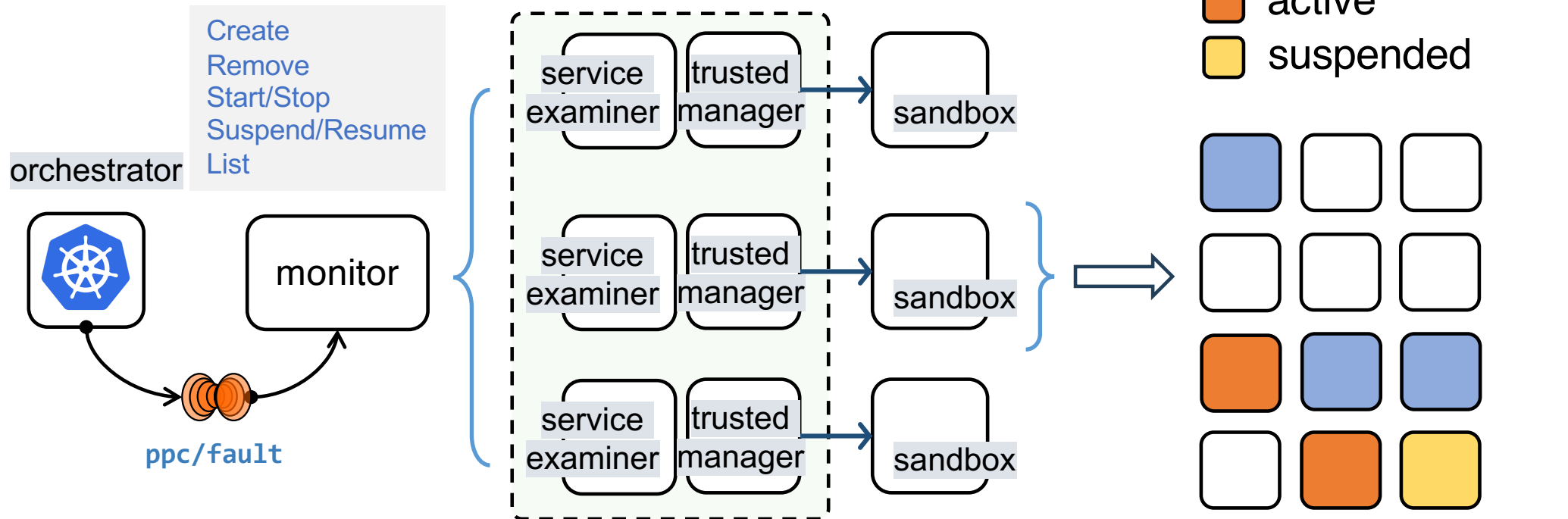




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- 3. Orchestration**
4. Programming API

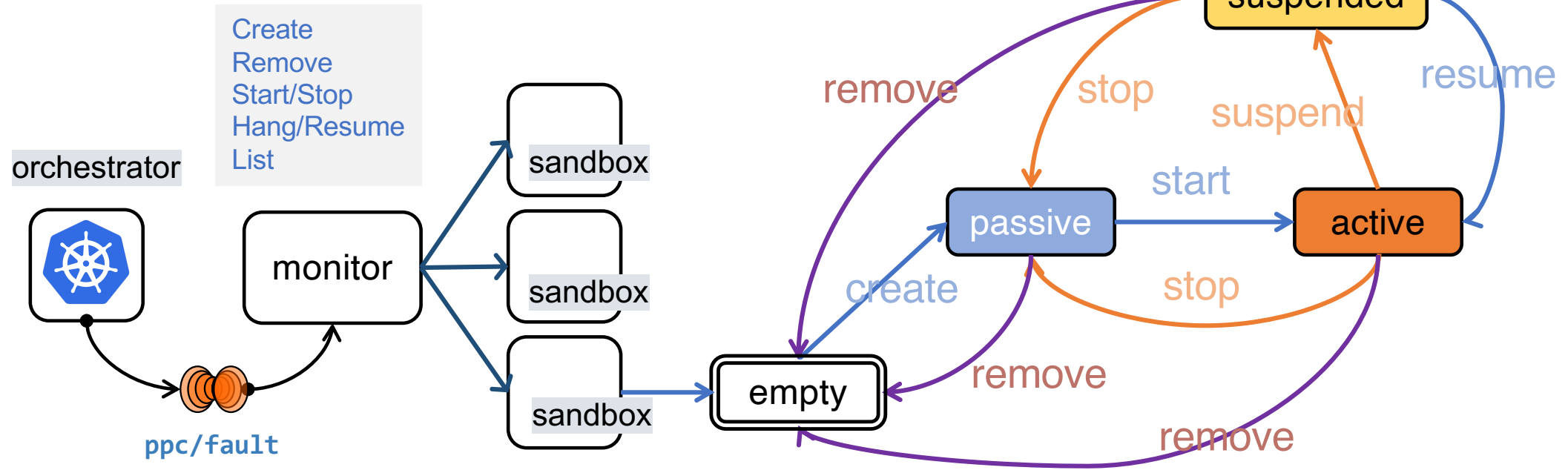
Orchestration

- Life-cycle state management
- Orchestrator

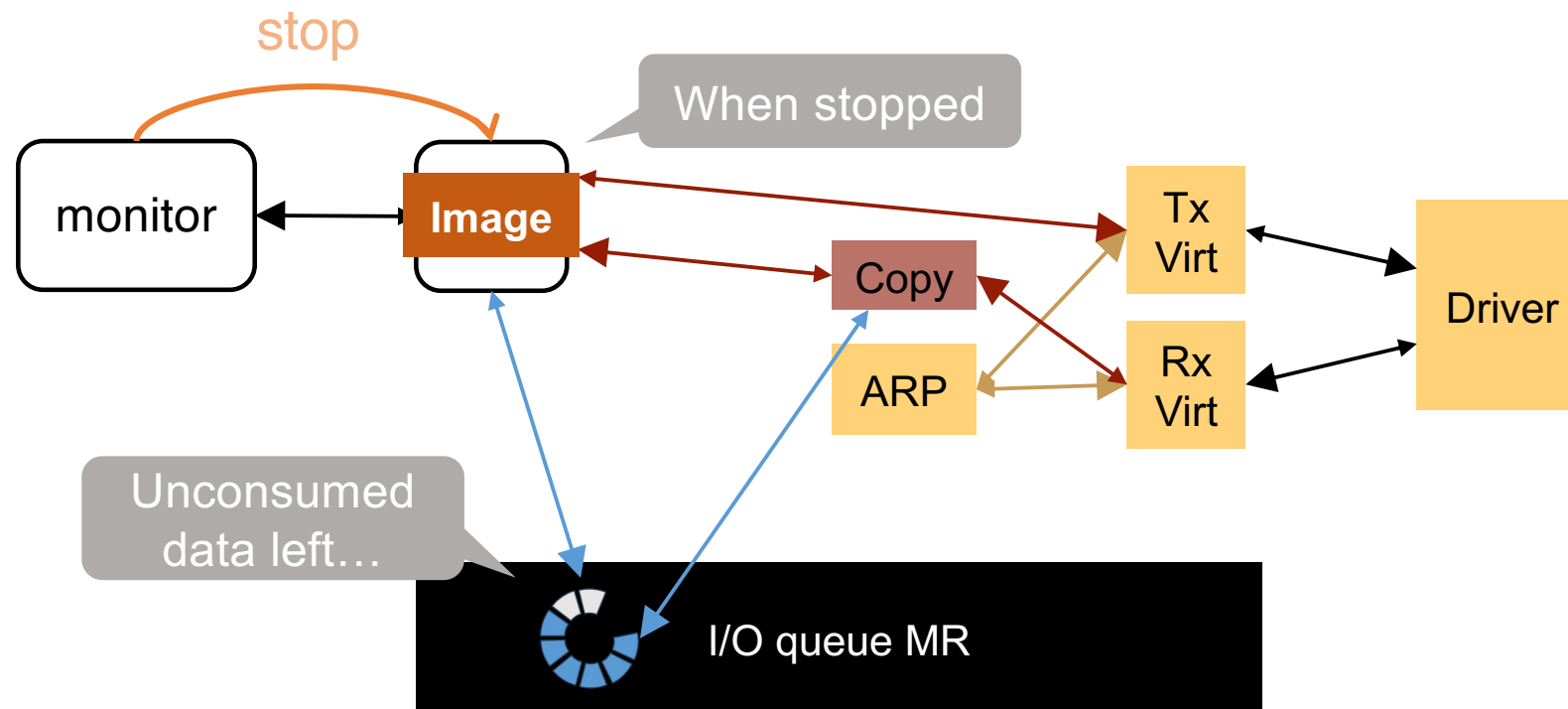


Orchestration

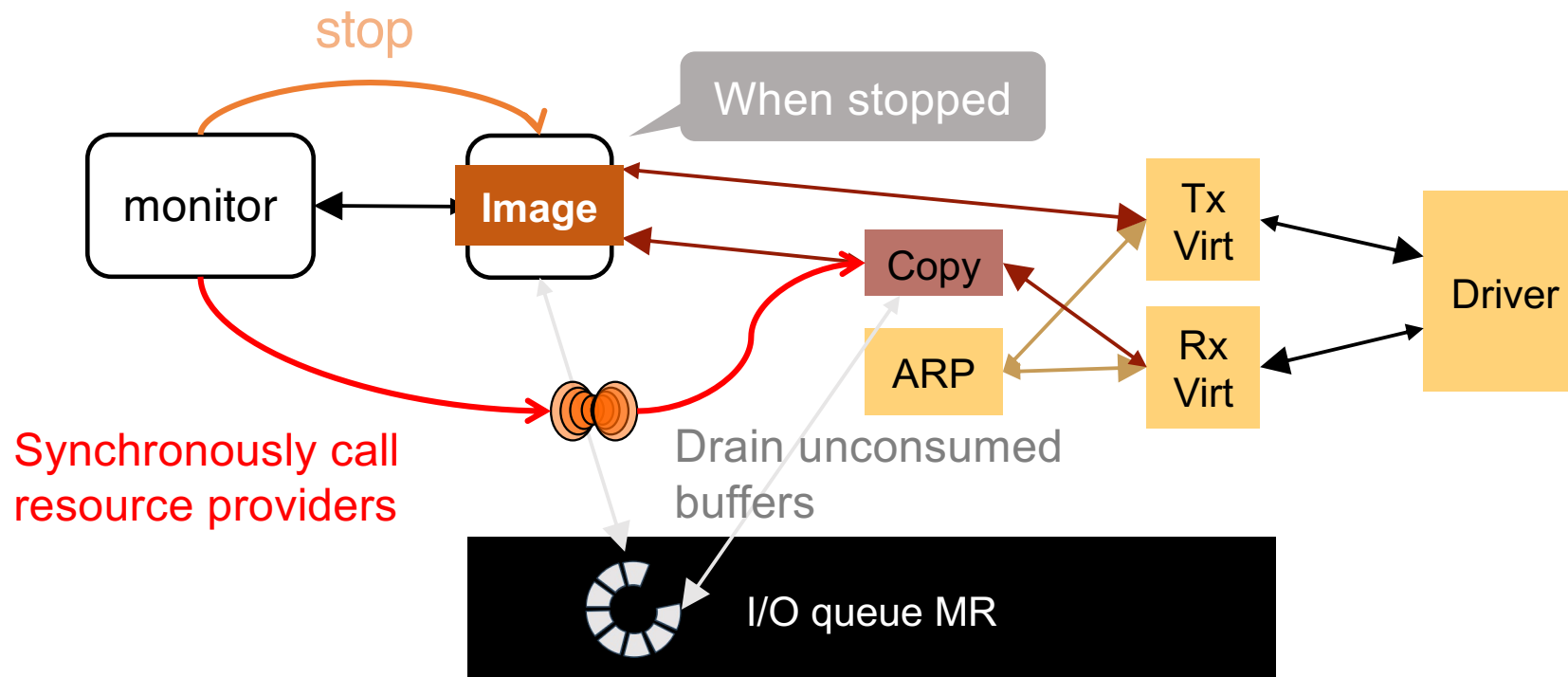
- Execution state changes by orchestrating operations



State management



State management: Plan





1. Microservice and seL4
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Programming API for microservices



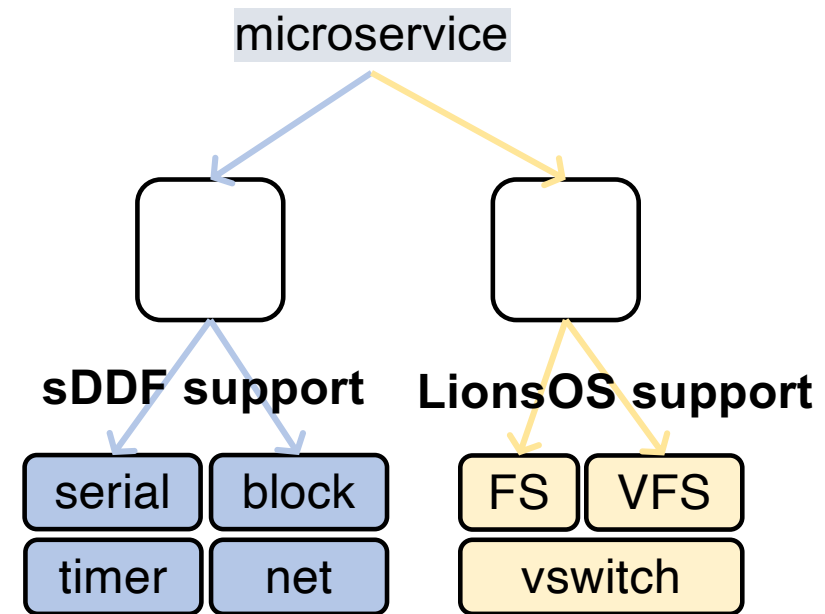
- **Native API**

- Flexible for building different OS personalities
- Not familiar to developers

libmicrokit

```
void init(void)
{
    microkit_dbg_puts("hello, world\n");
}

void notified(microkit_channel ch)
{
}
```



Unikraft: fast, specialized unikernels the easy way

Authors:  [Simon Kuenzer](#),  [Vlad-Andrei Bădoiu](#),  [Hugo Lefeuve](#),  [Sharan Santhanam](#),  [Alexander Jung](#),
 [Gauthier Gain](#),  [Cyril Soldani](#),  [Costin Lupu](#),  [Stefan Teodorescu](#),  [Costi Răducanu](#), [+ 5](#) [Authors](#)
[Info & Claims](#)

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<https://doi.org/10.1145/3447786.3456248>

Applications	NGINX, SQLite, Redis, memcached, Click modular router, lighttpd (ongoing).
Frameworks	Intel DPDK, TensorFlow Lite, PyTorch.
Compiled Languages	C/C++, Go, Web Assembly (WAMR), Lua, Java/OpenJDK (ongoing), Rust (ongoing)
Interpreted Languages	Python, Micropython, Ruby, JavaScript/v8 (ongoing).

Table 3. Applications, frameworks and languages currently supported by Unikraft.

Experimental Carrels support for Unikraft



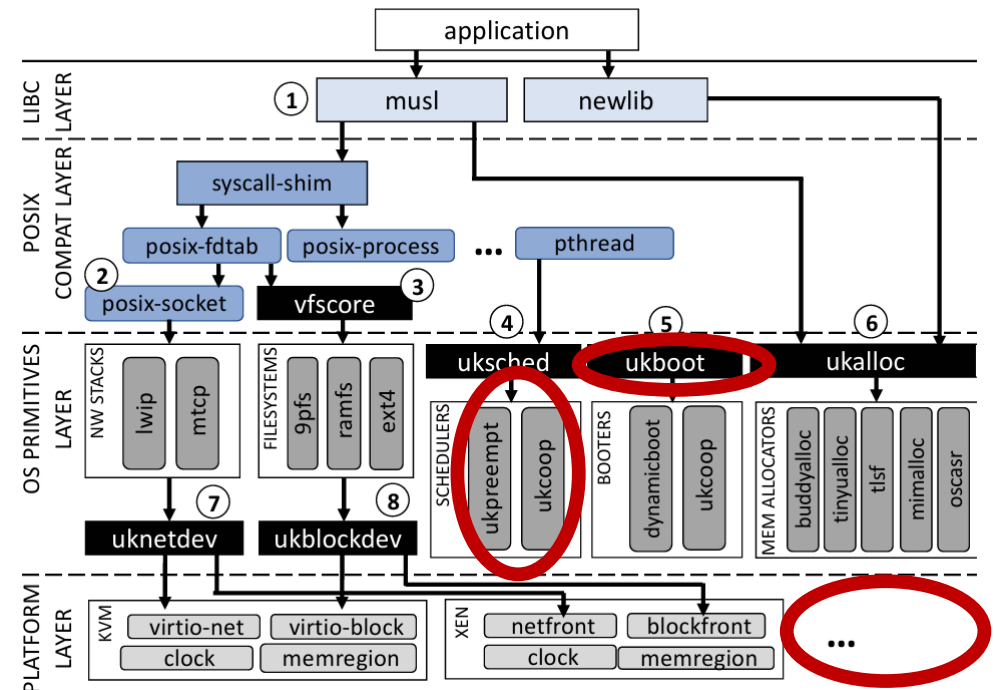
- lib/uksched, lib/ukschedcoop: +33 LoC
- lib/ukpcpuvar/arch/arm64: +38,-9 LoC

Patch needed

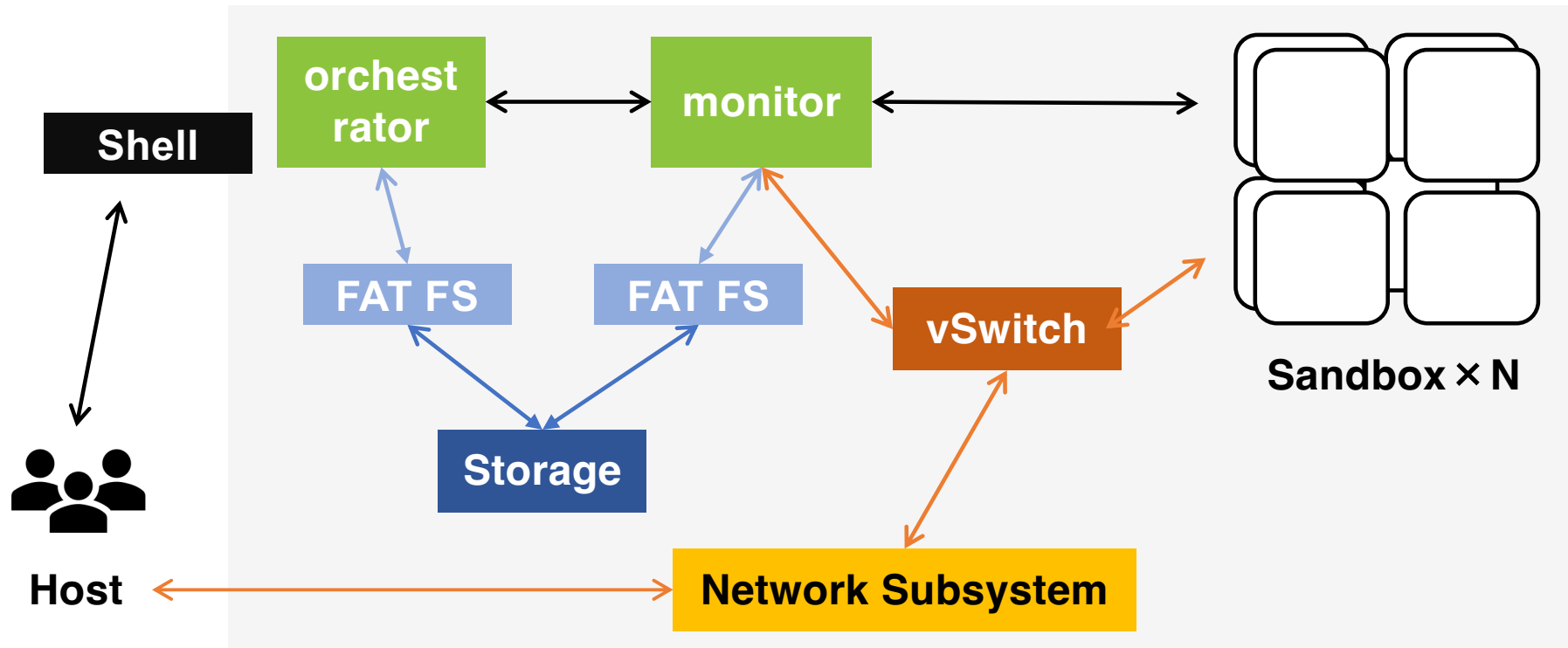
- plat/carrels: +1,101 LoC
- drivers/sddf: +530 LoC
 - network
 - timer
 - serial

New

plat/carrels



Demo



Questions?

Thanks for listening!

